



Knox Grammar School

2021

**Trial Higher School Certificate
Examination**

Name: _____

Teacher: _____

Year 12 Extension 2 Mathematics

General Instructions

- Reading time – 10 minutes
- Working time – 3 hours
- Write using blue or black pen only
- Board approved calculators may be used
- The official NESA Reference Sheet is provided
- In Questions 11-16, show relevant mathematical reasoning and/or calculations.

Section I ~ Pages 3-6

- 10 marks
- Attempt Questions 1 – 10
- Allow about 15 minutes for this section

Section II ~ Pages 7-15

- 90 marks
- Attempt Questions 11 – 16
- Allow about 2 hours 45 minutes for this section

Teachers:

Mr Bradford (Examiner)

Ms Yun

Mr Vuletich

Write your name, your Teacher's Name and your Student Number on the front cover of each answer booklet

Number of Students in Course: 31

This examination is based on the CSSA 2021 Extension 2 paper and modified in accordance with the CSSA directives:

Examinations can be compressed by removing some questions to shorten the examination. Schools should only upload/scan the relevant question. The CSSA Trial HSC Examination Timetable is to be adhered to; this includes the security period.

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Section I

10 marks

Attempt questions 1 – 10

Allow about 15 minutes for this section

Use the multiple-choice answer sheet for Questions 1-10.

1. Consider the statement: “If an animal is a bird, then it can fly or swim.”

What is the contrapositive statement?

- (A) If an animal cannot fly or cannot swim, then it is a bird.
- (B) If an animal cannot fly or cannot swim, then it is not a bird.
- (C) If an animal cannot fly and cannot swim, then it is a bird.
- (D) If an animal cannot fly and cannot swim, then it is not a bird.

2. Recall that nC_r is defined for non-negative integers r and n where $0 \leq r \leq n$.

Consider the equation $\frac{{}^{100}C_x}{{}^{x-1}C_{99}} = \frac{1}{x^{99}}$. How many real solutions in x does this equation possess?

- (A) 0
- (B) 1
- (C) 2
- (D) infinite

3. What is the angle between the vectors $\underline{u} = 2\underline{i} - \underline{j} + \underline{k}$ and $\underline{v} = \underline{i} + 3\underline{j} + 2\underline{k}$, to the nearest degree?

- (A) 77°
- (B) 83°
- (C) 84°
- (D) 96°

4. $A(1, 2, 2)$, $B(3, -12, 4)$, $C(1, 2, 0)$ and $D(3, -12, 0)$ are four position vectors. What is the vector projection of $\overrightarrow{AB}$ onto $\overrightarrow{CD}$?
- (A) $2\hat{i} - 14\hat{j} + 2\hat{k}$
- (B) $2\hat{i} - 14\hat{j} + 4\hat{k}$
- (C) $2\hat{i} - 14\hat{j}$
- (D) $-2\hat{i} + 14\hat{j}$
5. For all non-zero integers x and y , if $x > y$ then $\frac{1}{x} < \frac{1}{y}$. What is a counter-example to the above statement?
- (A) $x = 2, y = -1$
- (B) $x = 0, y = 0$
- (C) $x = 4, y = 3$
- (D) $x = -2, y = 1$
6. A particle is moving in simple harmonic motion with displacement x metres. Its acceleration $\ddot{x}$ is given by $\ddot{x} = -4x + 3$. What are the centre and period of motion?
- (A) centre of motion = 3, period = $\frac{\pi}{2}$
- (B) centre of motion = -3 , period = π
- (C) centre of motion = $\frac{3}{4}$, period = π
- (D) centre of motion = $\frac{3}{4}$, period = $\frac{\pi}{2}$

7. It is given that $z = 2 + i$ is a root of $z^3 + az^2 - bz + 5 = 0$, where a and b are real numbers.

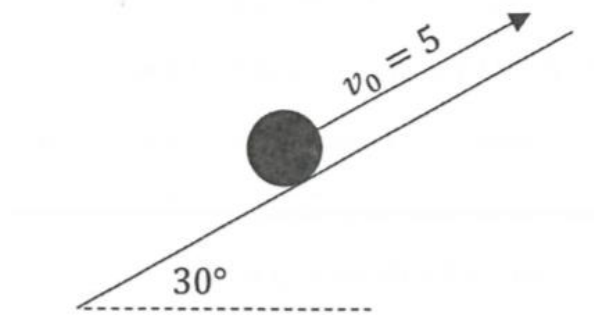
What is the value of a ?

- (A) -5
- (B) -3
- (C) 3
- (D) 5

8. Which integral has the smallest value?

- (A) $\int_0^{\frac{\pi}{4}} (\sin x)^2 dx$
- (B) $\int_0^{\frac{\pi}{4}} (\cos x)^2 dx$
- (C) $\int_0^{\frac{\pi}{4}} \sin x \cos x dx$
- (D) $\int_0^{\frac{\pi}{4}} \sin x \tan x dx$

9. A ball of mass m kg is observed rolling up a frictionless ramp, inclined at an angle of 30° to the horizontal. When first observed, the ball's velocity is 5 m/s.
Through what further distance will the ball roll up the ramp?



- (A) $\sqrt{3}$ metres
 (B) $m\sqrt{3}$ metres
 (C) 2.5 metres
 (D) $2.5m$ metres
10. What value of a will minimise the integral $\int_0^1 (x^2 - a)^2 dx$?
- (A) $a = \frac{1}{2}$
 (B) $a = \frac{1}{\sqrt{2}}$
 (C) $a = \frac{4}{45}$
 (D) $a = \frac{1}{3}$

End of Section I

Section II

90 marks

Attempt questions 11 – 16

Allow about 2 hours 45 minutes for this section

Answer each question in a separate writing booklet.

In Questions 11 – 16, your responses should include relevant mathematical reasoning and/or calculations.

Question 11	(15 marks) Use a SEPARATE writing booklet	Marks
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(a) Given $w = 2 + 5i$ and $z = 4 - 3i$, evaluate

(i) $ w + \bar{z} $	2
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(ii) $(w + \bar{z})(\bar{w} + z)$	2
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(b) Find the square roots of $15 - 8i$.	3
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(c) Use the substitution $t = \tan \frac{\theta}{2}$ to evaluate $\int_0^{\frac{\pi}{2}} \frac{d\theta}{1 + \sin \theta + \cos \theta}$.	4
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(d) (i) Write down all the roots of $z^7 - 1 = 0$ in the form $re^{i\theta}$ where $r > 0$ and $-\pi < \theta \leq \pi$.	2
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(ii) Hence, prove that $\cos \frac{2\pi}{7} + \cos \frac{4\pi}{7} + \cos \frac{6\pi}{7} = -\frac{1}{2}$	2
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End of Question 11

Question 12 (15 marks) Use a SEPARATE writing booklet

Marks

(a) Use integration by parts to find $\int x3^x dx$. **3**

(b) By writing $\frac{8-2x}{(1+x)(4+x^2)}$ in the form $\frac{A}{1+x} + \frac{Bx+C}{4+x^2}$, evaluate $\int_0^4 \frac{8-2x}{(1+x)(4+x^2)} dx$. **4**

(c) On the same Argand diagram, draw a neat sketch of $|z-4-4i|=2$ and $\arg(z)=\frac{\pi}{4}$. **4**

Hence write down all the values of z which satisfy simultaneously

$$|z-4-4i|=2 \text{ and } \arg(z)=\frac{\pi}{4}.$$

(d) Find the scalar projection of the vector $\underline{u} = \underline{i} - 2\underline{j} + \underline{k}$ onto $\underline{v} = 4\underline{i} - 4\underline{j} + 7\underline{k}$. **2**

(e) Given $\underline{a} = \begin{pmatrix} -1 \\ 3 \\ 4 \end{pmatrix}$ and $\underline{b} = \begin{pmatrix} -2 \\ 1 \\ -4 \end{pmatrix}$, and $\underline{a} - \underline{b} + 2\underline{c} = \underline{0}$, find $\underline{c}$. **2**

End of Question 12

Question 13 (15 marks) Use a SEPARATE writing booklet

Marks

- (a) (i) Suppose a and b are positive integers, where a is even and b is odd. Show that the sum of a and b is odd. **1**

For positive integers m and n , consider the propositions:

p : $m + n$ is even

q : m and n are both even

r : m and n are both odd

- (ii) Write in symbolic form the compound proposition P where **1**

P : If $m + n$ is even, then m and n are both even or m and n are both odd.

You may use $\vee$ for 'or' and $\wedge$ for 'and' where appropriate.

- (iii) Write both in symbolic form and as an English sentence, the contrapositive to the proposition P in part (ii). **2**

- (iv) Hence explain why the proposition P is true. **1**

- (b) If x and y are positive integers with $x > y$, prove that $6(x + y)^2 - 2(x - y)^2$ is divisible by four. **1**

(c) Let $I_1 = \int_0^{\pi} \frac{x \sin x dx}{1 + \cos^2 x}$ and $I_2 = \int_0^{\pi} \frac{(\pi - x) \sin x dx}{1 + \cos^2 x}$.

- (i) Using the substitution $u = \pi - x$ show that $I_1 = I_2$. **2**

- (ii) Hence, or otherwise, evaluate I_1 . **2**

Question 13 continues on page 10

Question 13 (continued)

(d) A particle is travelling in a straight line. Its displacement, x cm, from O at a given time t seconds after the start of its motion is given by $x = 3 + \sin^2 t$.

(i) Prove that the particle is undergoing simple harmonic motion. 2

(ii) Find the period of the motion. 1

(iii) Find the total distance travelled by the particle in the first π seconds. 2

End of Question 13

Question 14 (15 marks) Use a SEPARATE writing booklet

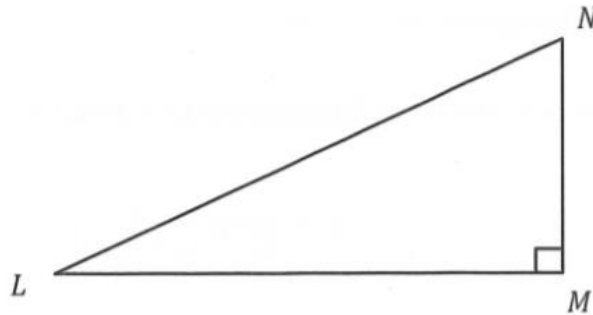
Marks

- (a) Prove $\log_3 7$ is irrational. 2
- (b) The scalar product of $\hat{i} - 2\lambda\hat{j} - \hat{k}$, and the sum of $\hat{i} - \lambda\hat{k}$ and $\lambda\hat{i} + 2\hat{j} - \hat{k}$, is six. Find λ . 2
- (c) Prove by mathematical induction $(2n)! < (n!)^2 \times 4^{n-1}$ for all positive integers $n \geq 5$. 4
- (d) Let $\overrightarrow{OA} = \underline{a}$, $\overrightarrow{OB} = \underline{b}$ and $\overrightarrow{OC} = 3\underline{a} + 2\underline{b}$.
- (i) Prove that if $\overrightarrow{OD} = \frac{1}{5}\overrightarrow{OC}$ then D lies on AB . 2
- (ii) Is the point D closer to point A or point B ? Justify your answer. 1
- (e) (i) Given $z = \cos \theta + i \sin \theta$, prove that $z^n - \frac{1}{z^n} = 2i \sin n\theta$, where $n \in \mathbb{Z}$. 1
- (ii) Hence, by considering the expansion of $\left(z - \frac{1}{z}\right)^5$, find the values of a , b and c 3
such that $\sin^5 \theta = a \sin 5\theta + b \sin 3\theta + c \sin \theta$.

End of Question 14

Question 15 (15 marks) Use a SEPARATE writing booklet**Marks**

(a)



In $\triangle LMN$, let $\overrightarrow{LM} = \underline{a}$ and $\overrightarrow{MN} = \underline{b}$.

3

By finding an expression for the side length LN in terms of the vectors $\underline{a}$ and $\underline{b}$, or

otherwise, prove that $|\overrightarrow{LN}|^2 = |\overrightarrow{LM}|^2 + |\overrightarrow{MN}|^2$.

(b) By evaluating the integral, show that

$$\int x^2 \sqrt{1-x^2} dx = \frac{\sin^{-1}(x) + \sqrt{1-x^2} (2x^3 - x)}{8} + C$$

3

(c) It is given that $\frac{1}{k(k+1)} = \frac{1}{k} - \frac{1}{k+1}$ for $k \in \mathbb{N}$.

(i) Prove that $\frac{1}{(k+1)^2} < \frac{1}{k(k+1)}$.

1

(ii) If $x_1, x_2, x_3, \dots, x_n$ are positive integers, not necessarily consecutive, such that

3

$1 < x_1 < x_2 < x_3 < \dots < x_n$, prove that $\frac{1}{x_1^2} + \frac{1}{x_2^2} + \frac{1}{x_3^2} + \dots + \frac{1}{x_{n-1}^2} < 1$.

Question 15 continues on page 13

Question 15 (continued)

- (d) A particle of mass m kg is moving vertically downwards in a medium which exerts a resistive force equal to mkv^2 , where v is the particle's speed and $k > 0$ is a positive constant. The particle is released from rest at O and its terminal velocity is U .

- (i) By applying Newton's 2nd Law, show that the distance it has fallen below O is given by: 2

$$x = \frac{1}{2k} \ln \left| \frac{g}{g - kv^2} \right|.$$

- (ii) Prove that the time taken, T , for the particle to fall from O to when its velocity is half of its terminal velocity, U , is given by: 3

$$T = \frac{U}{2g} \ln 3.$$

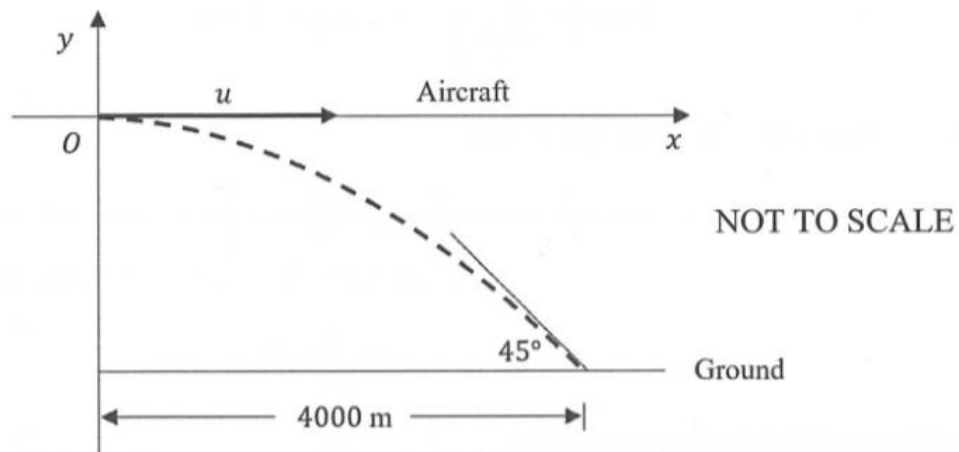
End of Question 15

Question 16 (15 marks) Use a SEPARATE writing booklet

Marks

- (a) An aircraft flying horizontally at u m/s delivers an emergency medical supply package that hits the ground 4000 m away, measured horizontally. The package experiences an air resistance of $0.1v$ where v is the velocity at time t and g is the acceleration due to gravity.

The package hits the ground at an angle of 45° to the horizontal.



The horizontal and vertical components of acceleration are given by the differential equations $\ddot{x} = -0.1\dot{x}$ and $\ddot{y} = -g - 0.1\dot{y}$ respectively.

- (i) By solving these differential equations, show that t seconds after release, the position vector, $\vec{r}(t)$, is given by:

5

$$\vec{r}(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} 10u(1 - e^{-0.1t}) \\ 100g(1 - e^{-0.1t}) - 10gt \end{pmatrix}$$

- (ii) Using $g = 10 \text{ m/s}^2$, find the time when the package hits the ground.
Give your answer correct to 1 decimal place.

3

Question 16 continues on page 15

Question 16 (continued)

- (b) The lengths of the sides of a right triangle are a , b and c , where c is the length of the hypotenuse. Prove the Pythagorean Inequality Theorem: $a^3 + b^3 < c^3$. 2

- (c) (i) Given that $I_{2n+1} = \int_0^1 x^{2n+1} e^{x^2} dx$ where n is a positive integer, 2
 prove that $I_{2n+1} = \frac{e}{2} - nI_{2n-1}$.

- (ii) Hence, or otherwise, prove that $2 \int_0^1 x^{2n-1} (1+x^2) e^{x^2} dx \leq e$ for $n \in \mathbb{N}$. 3

End of Paper



2021 Year 12 Mathematics Extension 2 Task 4 SOLUTIONS

1 of 22

Suggested Solution (s)	Comments	Suggested Solution (s)	Comments
SECTION I			
1. Let p, q & r be the statements p: An animal is a bird q: An animal can fly r: An animal can swim The compound statement in symbolic form is $p \rightarrow (q \vee r)$ Its contrapositive is: $\sim(q \vee r) \rightarrow \sim p$ $\Rightarrow \sim q \wedge \sim r \rightarrow \sim p$ $\Rightarrow \text{If an animal cannot fly and (if an animal) cannot swim, then the animal is not a bird.}$ Of the alternatives (D) is correct. Recall, in logic, 'or' as a conjunction has an inclusive sense, and this allows for the possibility that the animal can swim when it can't fly and vice versa. 2. $\frac{100 \cdot x_c}{x-1 \cdot c_{99}} = \frac{100 \cdot x!}{(x-100)! \cdot 100!}$ $= \frac{100 \cdot x!}{(x-100)! \cdot 100!} \times \frac{99! \cdot (x-100)!}{(x-1)!}$ $= \frac{x \cdot 100! \cdot (x-1)! \cdot (x-100)!}{100! \cdot (x-1)! \cdot (x-100)!} \text{ or } x$ So we have $x = \frac{1}{99}$ $\Rightarrow x^{100} - 1 = 0$	1. D 6. C 2. A 7. B 3. C 8. A 4. C 9. C 5. A 10. D De Morgan's Laws	Solutions given by $x = \cos\left(\frac{2k\pi}{100}\right)$ Real sol'ns correspond to $k=0$ & $k=50$ only, that is, $x=1$ & $x=-1$. However ${}^n C_r$ is only defined for $n \geq r$; hence, x_c is only defined for $x \geq 100$; $x \in \mathbb{N}$. So the original equation has no real solutions. $\therefore$ (A) 3. If θ is the angle between $\vec{u}$ & $\vec{x}$, then $\theta = \cos^{-1}\left(\frac{\vec{u} \cdot \vec{x}}{ \vec{u} \vec{x} }\right)$ $= \cos^{-1}\left(\frac{1}{\sqrt{6} \cdot \sqrt{14}}\right) \text{ or } \cos^{-1}\left(\frac{1}{\sqrt{84}}\right)$ $= 83.736... \approx 84^\circ \therefore$ (C) 4. $\vec{AB} = (2, -14, 2)$ & $\vec{CD} = (2, -14, 0)$ $\text{Proj}_{\vec{CD}} \vec{AB} = \frac{\vec{AB} \cdot \vec{CD}}{\vec{CD} \cdot \vec{CD}} \cdot \vec{CD}$ $\therefore$ (C) $= \frac{198}{198} (2, -14, 0) \text{ or } 2\hat{i} - 14\hat{j}$ 5. $2 > -1 \rightarrow \frac{1}{2} < -1$ is false with $2, -1 \in \mathbb{Z} \setminus \{0\}$. Here $p: 2 > 1$ & $q: \frac{1}{2} < -1$ The truth value of p is true or 1 & the truth value of q is false or 0. Consequently, the truth value of the implication $p \rightarrow q$ is false. So (A) B: $\begin{matrix} F & F \\ \text{inputs} \end{matrix} \Rightarrow$ implication is true C: $\begin{matrix} T & T \end{matrix} \Rightarrow$ implication is true D: $\begin{matrix} F & T \end{matrix} \Rightarrow$ implication is true	$k=0, 1, \dots, 99$

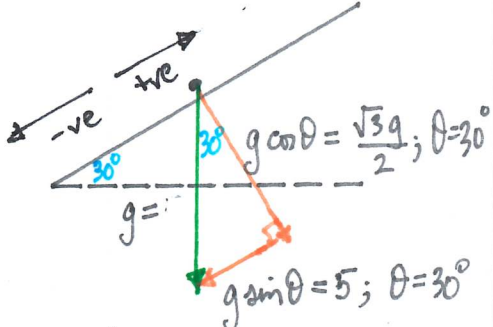


Suggested Solution (s)	Comments	Suggested Solution (s)	Comments
6. $\ddot{x} = -4(x - \frac{3}{4})$ or $= -(2)^2(x - \frac{3}{4})$ $\therefore x_0 = \frac{3}{4} \quad \therefore (C)$ $\tau = \frac{2\pi}{2} \text{ or } \pi$ 7. Product of roots = -5 Given $2+i$ is a root, then $2-i$ is also a root as the polynomial equation satisfies the criteria of the CONJUGATE ROOT THEOREM. If the remaining root is α, then $(2+i)(2-i) \cdot \alpha = -5$ $\Rightarrow 5\alpha = -5 \text{ or } \alpha = -1$. So roots are $2 \pm i, -1$ & sum of roots, $\sum \alpha_i = -a$ $\Rightarrow (2+i) + (2-i) + (-1) = -a$ $\Rightarrow a = -3 \quad \therefore (B)$ ALTERNATIVE: Coefficients of polynomial are real and so $2+i$ is also a root Noting $(z-\alpha)(z-\bar{\alpha}) = z^2 - (\alpha+\bar{\alpha})z + \alpha\bar{\alpha}$ $= z^2 - 2\text{Re}(\alpha)z + \alpha ^2$ For $\alpha = 2+i$, then $z^2 - 4z + 5$ is a factor of $z^3 + az^2 - bz + 5$. So $z^3 + az^2 - bz + 5 = (z-c)(z^2 - 4z + 5)$ where c is the remaining root $\therefore -5c = 5 \text{ or } c = -1$. Hence, sum of roots = $(2+i) + (2-i) + (-1) = -a \Rightarrow a = -3$. So (B)	OF type $\ddot{x} = -n^2(x-x_0)$ $\tau = \frac{2\pi}{n}$ $x_0 = \text{centre of motion}$ Relationships between roots & coefficients Relationships between roots & relationships Conjugate Root theorem Factor theorem $\sum \alpha_i = -\frac{a}{1}$	8. For $x \in [0, \frac{\pi}{4}]$ all integrands are non-negative with each equally zero only when $x=0$. So all integrals, when evaluated are positive. Now $\sin x \leq \cos x$ on $[0, \frac{\pi}{4}]$ with equality only achieved at $x = \frac{\pi}{4}$. $\therefore \sin^2 x \leq \cos^2 x \dots (I)$ & $\sin x \cdot \sin x \leq \cos x \cdot \sin x$ $\Rightarrow \sin^2 x \leq \sin x \cdot \cos x \dots (II)$ Finally $\frac{1}{\sqrt{2}} \leq \cos x \leq 1$ on $[0, \frac{\pi}{4}]$ So, $1 \leq \frac{1}{\cos x} \leq \sqrt{2}$ $\therefore \sin x \cdot \tan x = \frac{\sin^2 x}{\cos x}$ $= \sin^2 x \cdot \frac{1}{\cos x}$ Upon multiplying the inequality $1 \leq \frac{1}{\cos x} \leq \sqrt{2}$ by $\sin^2 x \geq 0$ $\Rightarrow \sin^2 x \leq \sin x \cdot \tan x \leq \sqrt{2} \cos^2 x \dots (III)$ From inequalities (I), (II) & (III), we conclude that $\int_0^{\frac{\pi}{4}} \sin^2 x \cdot dx$ has the least value. $\therefore (A)$ Graphical Approach available.	as $\sin x \geq 0$ on $[0, \frac{\pi}{4}]$ $x \in [0, \frac{\pi}{4}]$



2021 Year 12 Mathematics Extension 2 Task 4 SOLUTIONS

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Suggested Solution (s)	Comments	Suggested Solution (s)	Comments
9.  Taking the positive sense in the direction of motion; here, up the ramp, then: $\ddot{x} = -g \sin \theta$ $\ddot{x} = -5$ $\Rightarrow \dot{x} = C_1 - 5t \quad \& \quad \dot{x} = 5 \text{ m/s when } t = 0$ $\Rightarrow \dot{x} = 5 - 5t \quad \therefore C_1 = 5$ $\Rightarrow x = 5t - \frac{5}{2}t^2 + C_2 \quad \& \quad x = 0 \text{ when } t = 0$ So $\begin{cases} \dot{x} = 5 - 5t \\ x = 5t - \frac{5}{2}t^2 \end{cases} \Rightarrow C_2 = 0$ Object comes to rest when $t = 1$ $\& \quad x(1) = 5 - \frac{5}{2}$ or 2.5 Hence, ball rolls a further 2.5m up ramp. $\therefore$ (C)	$\theta = 30^\circ$, $g = 10 \text{ m/s}^2$ $\dot{x} = 0$	10. $\int_0^1 (x^2 - a)^2 dx$ $= \int_0^1 (x^4 - 2ax^2 + a^2) dx$ $= \left[\frac{x^5}{5} - \frac{2a}{3}x^3 + a^2x \right]_0^1$ $= a^2 - \frac{2a}{3} + \frac{1}{5}$ $= \left(a - \frac{1}{3}\right)^2 + \frac{1}{5} - \frac{1}{9} \quad \text{OR}$ $\left(a - \frac{1}{3}\right)^2 + \frac{4}{45}$ This algebraic expression is minimised when $a = \frac{1}{3}$. ALTERNATIVE: Let $b = a^2 - \frac{2a}{3} + \frac{1}{5}$. b is minimised when $\frac{db}{da} = 0$. This implies $2a - \frac{2}{3} = 0$ $\Rightarrow a = \frac{1}{3}$. $\therefore$ (D)	



Suggested Solution (s)	Comments	Suggested Solution (s)	Comments
A11 SECTION II (a) (i) $w = 2+5i$; $z = 4-3i$ $\therefore w+\bar{z} = (2+5i) + (4+3i)$ $= 6+8i$ $= \sqrt{6^2+8^2}$ or 10 (ii) Noting $\overline{w+\bar{z}} = \bar{w} + z$ $= \bar{w} + z$ Then $(w+\bar{z})(\bar{w}+z) = (\bar{w}+z)(w+\bar{z})$ $= w+\bar{z} ^2$ $= 10^2$ or 100 ALTERNATIVE: $(w+\bar{z})(\bar{w}+z) = (6+8i)(6-8i)$ $= 6^2+8^2$ or 100 (b) Let $x+iy$ be a square root of $15-8i$. Then $(x+iy)^2 = 15-8i$ $\Rightarrow x^2-y^2 = 15$ upon equating $xy = -4$ real & imaginary parts By inspection $x = \pm 4$ & $y = \mp 1$ Hence square roots are $4-i$ & $-4+i$, i.e. $\pm(4-i)$ ALTERNATIVE: Substitute $y = -\frac{4}{x}$ into $x^2-y^2 = 15$ $\therefore x^2 - \frac{16}{x^2} = 15$ $\Rightarrow x^4 - 15x^2 - 16 = 0$ $\Rightarrow (x^2-16)(x^2+1) = 0$	✓ process ✓ answer Properties of Conjugate $z\bar{z} = z ^2$ ✓ process ✓ answer $-8i^2 = 8$ ✓ simultan. equations ✓ correct answers ⊗ by x^2	(c) $t = \tan \frac{\theta}{2}$, then $d\theta = \frac{2dt}{1+t^2}$ ALTERNATIVE: $\frac{dt}{d\theta} = \frac{1}{2} \sec^2 \frac{\theta}{2}$ $= \frac{1}{2} (1 + \tan^2 \frac{\theta}{2})$ $\frac{dt}{d\theta} = \frac{1}{2} (1+t^2)$ $\Rightarrow \frac{d\theta}{dt} = \frac{2}{1+t^2}$ or equivalently, $d\theta = \frac{2dt}{1+t^2}$ When $\begin{cases} \theta = 0, & t = 0 \\ \theta = \frac{\pi}{2}, & t = 1 \end{cases}$ $\sin \theta = \frac{2t}{1+t^2}$ & $\cos \theta = \frac{1-t^2}{1+t^2}$ $\therefore$ integral becomes: $\int_0^1 \frac{2/(1+t^2) dt}{1 + \frac{2t/(1+t^2) + (1-t^2)/(1+t^2)}{2}}$ $= \int_0^1 \frac{2 dt}{2+2t}$ OR $\int_0^1 \frac{dt}{1+t}$ $= \ln 1+t \Big _0^1$ or $\ln 2$ (d) (i) Roots are given by: $z_k = r^n e^{i(\frac{\theta+2k\pi}{n})}; k=0,1,2,\dots,6$ $z_k = e^{i(\frac{2k\pi}{7})};$ $z_0 = 1$ $z_5 = e^{i(\frac{10\pi}{7})} = e^{i(-\frac{4\pi}{7})}$ $z_1 = e^{i(\frac{2\pi}{7})}$ $z_6 = e^{i(\frac{12\pi}{7})} = e^{i(-\frac{2\pi}{7})}$ $z_2 = e^{i(\frac{4\pi}{7})}$ $z_3 = e^{i(\frac{6\pi}{7})}$ $z_4 = e^{i(\frac{8\pi}{7})} = e^{i(-\frac{6\pi}{7})}$	Pythagorean Identity ✓ correct differential 1 mark 1 mark for correct integrand 1 mark for correct ans. $n=7$ $r=1$ $\theta = \text{Arg}(1) = 0$ ✓ progress ✓ for correct answers with principal arguments

$\Rightarrow x = \pm 4$ only; $x \in \mathbb{R}$
whereupon $y = \mp 1$ respectively



Suggested Solution (s)	Comments	Suggested Solution (s)	Comments
Q11 (a) (ii) $\sum \alpha_i = 0$ $\therefore 1 + e^{i(\frac{2\pi}{7})} + e^{i(\frac{4\pi}{7})} + e^{i(\frac{6\pi}{7})} + e^{i(\frac{8\pi}{7})} + e^{i(\frac{10\pi}{7})} + e^{i(\frac{12\pi}{7})} = 0$ $\Rightarrow 1 + 2\cos(\frac{2\pi}{7}) + 2\cos(\frac{4\pi}{7}) + 2\cos(\frac{6\pi}{7}) = 0$ $\Rightarrow \cos(\frac{2\pi}{7}) + \cos(\frac{4\pi}{7}) + \cos(\frac{6\pi}{7}) = -\frac{1}{2}$ Question 12 (a) Let $u = x \Rightarrow du = dx$ & let $dv = 3^x dx \Rightarrow v = \frac{2^x}{\ln(3)}$ $\int u dv = uv - \int v du$ $\therefore \int x 3^x dx = \frac{x 3^x}{\ln(3)} - \frac{1}{\ln(3)} \int 3^x dx$ $= \frac{x 3^x}{\ln(3)} - \frac{3^x}{(\ln(3))^2} + C$ $\frac{3^x}{\ln(3)} \left[x - \frac{1}{\ln(3)} \right] + C$ N.B. $\int a^x dx = \frac{a^x}{\ln(a)}$ for $a > 0$ & $a \neq 1$. (b) $\frac{8-2x}{(1+x)(4+x^2)} \equiv \frac{A}{1+x} + \frac{Bx+C}{4+x^2}$ $\Rightarrow 8-2x \equiv A(4+x^2) + (Bx+C)(1+x)$ When $x = -1$: $10 = 5A \Rightarrow A = 2$ Equating coefficients of x^2: $0 = A + B \Rightarrow B = -2$ Equating constants: $8 = 4A + C \Rightarrow C = 0$	Relationships between roots and coefficients $\frac{i\theta - i\theta}{e + e} = 2\cos\theta$ ✓ process ALTERNATIVE STRATEGIES AVAILABLE - SEE SUPPLEMENT Integration by Parts ✓ attempting house IP ✓✓ substantial progress ✓✓ correct solution ✓ for at most two correct values ✓✓ for all three correct values	$\therefore \int_0^4 \frac{8-2x}{(1+x)(4+x^2)} dx$ $= \int_0^4 \left(\frac{2}{1+x} - \frac{2x}{4+x^2} \right) dx$ $= 2\ln 1+x - \ln(4+x^2) \Big _0^4$ $= 2\ln(5) - \ln(20) + \ln(4)$ $= 2\ln(5) - \ln(4) - \ln(5) + \ln(4)$ $= \ln(5)$ (c) pole or singularity Cartesian form of circle is $(x-4)^2 + (y-4)^2 = 4 \dots (I)$ Cartesian form of ray is $y = x; x > 0 \dots (II)$ Solving simultaneously, $2(x-4)^2 = 4$ $\Rightarrow x = 4 \pm \sqrt{2}$ $\Rightarrow y = 4 \pm \sqrt{2}$ Hence $z = (4 \pm \sqrt{2}) + i(4 \pm \sqrt{2})$ or $z = (4 \pm \sqrt{2}, 4 \pm \sqrt{2})$	✓ correct integration $\ln(ab) = \ln(a) + \ln(b)$ ✓ correct answer ✓ correct sketch of circle ✓ correct sketch of ray excluding origin ✓ for simultaneous system ✓ for correct answers



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Suggested Solution (s)	Comments	Suggested Solution (s)	Comments
Q12(d) Scalar Projection of $\underline{u}$ onto $\underline{x}$ is given by $\frac{\underline{u} \cdot \underline{x}}{ \underline{x} }$ where $\underline{u} \cdot \underline{x} = 4 + 8 + 7$ or 19 & $\underline{x} = \sqrt{4^2 + (-4)^2 + 7^2}$ or 9 $\therefore$ scalar projection = $\frac{19}{9}$ (e) $\begin{pmatrix} -1 \\ 3 \\ 4 \end{pmatrix} - \begin{pmatrix} -2 \\ 1 \\ -4 \end{pmatrix} + 2 \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ $\Rightarrow \begin{cases} 2x + 1 = 0 \\ 2y + 2 = 0 \\ 2z + 8 = 0 \end{cases} \Rightarrow \begin{cases} x = -\frac{1}{2} \\ y = -1 \\ z = -4 \end{cases}$ $\therefore \underline{c} = \begin{pmatrix} -\frac{1}{2} \\ -1 \\ -4 \end{pmatrix}$ Question 13 (a) (i) Let $a = 2k_1$; $k_1 \in \mathbb{N}$; let $b = 2k_2 + 1$; $k_2 \in \mathbb{N}$. Then $a + b = 2k_1 + (2k_2 + 1)$ $= 2(k_1 + k_2) + 1$ $= 2K + 1$; $K = k_1 + k_2$ which is ODD by definition (ii) p: $m+n$ is even q: m and n are both even r: m and n are both odd $p \rightarrow (q \vee r)$	✓ for correct dot product ✓ correct answer ✓✓ for correct solution ✓ one careless error only appearing in solution ✓✓ for process Positive integers are closed under addition ✓ correct answer	(iii) We have $p \rightarrow (q \vee r)$ & its contrapositive is:- $\sim (q \vee r) \rightarrow \sim p$ $\Leftrightarrow \sim q \wedge \sim r \rightarrow \sim p$ If m and n are NOT both even AND if m and n are NOT both odd, then $m+n$ is NOT even. OR If one of m and n is even and the other is odd, then $m+n$ is ODD. This result was proven in part (i) and as an implication & its contrapositive are logically equivalent, proposition P is true. (b) $6(x+y)^2 - 2(x-y)^2$ $= 6x^2 + 12xy + 6y^2 - 2x^2 + 4xy + 2y^2$ $= 4x^2 + 16xy + 8y^2$ $= 4(x^2 + 4xy + 2y^2)$ $= 4M$; $M = x^2 + 4xy + 2y^2$ $\in \mathbb{N}$ $\therefore 4 \mid \{6(x+y)^2 - 2(x-y)^2\}$ See Over for (c)	$\vee \equiv$ or $\wedge \equiv$ and ✓ correct contrapositive symbolise de Morgan's Laws ✓ for correct contrapositive English form ✓ logical equivalence mandatory ✓ for proof Positive integers closed under $\oplus$ and $\otimes$



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Suggested Solution (s)	Comments	Suggested Solution (s)	Comments
Q13(c)(i) For $I_1 = \int_0^{\pi} \frac{x \sin x}{1 + \cos^2 x} dx$, Let $u = \pi - x$. When $x=0$ $(x=\pi-u)$ $u=\pi$ & $\Rightarrow du = -dx$ or When $x=\pi$ $u=0$ $dx = -du$ $\therefore I_1 = - \int_{\pi}^0 \frac{(\pi-u) \cdot \sin(\pi-u)}{1 + \cos^2(\pi-u)} du$ $= \int_0^{\pi} \frac{(\pi-u) \cdot \sin u}{1 + \cos^2 u} du$ $= \int_0^{\pi} \frac{(\pi-x) \cdot \sin x}{1 + \cos^2 x} dx$ $= I_2$ (ii) $I_1 + I_2 = \pi \int_0^{\pi} \frac{\sin x}{1 + \cos^2 x} dx$ $= -\pi \int_0^{\pi} \frac{-\sin x}{1 + \cos^2 x} dx$ $= -\pi \left[\tan^{-1}(\cos x) \right]_0^{\pi}$ $= -\pi \left[\tan^{-1}(-1) - \tan^{-1}(1) \right]$ $= -\pi \left[-2 \tan^{-1}(1) \right]$ $= 2\pi \cdot \frac{\pi}{4}$ or $\frac{\pi^2}{2}$ ✓ for process	✓ for process $\sin(\pi-\theta) = \sin \theta$; $\cos(\pi-\theta) = -\cos \theta$ $-\int_a^b f = \int_b^a f$ changing dummy variable Formally, integration by substitution with $u = \cos x$ $-\pi \int_1^{-1} \frac{du}{1+u^2}$ or $\pi \int_{-1}^1 \frac{du}{1+u^2}$ $= 2\pi \int_0^1 \frac{du}{1+u^2}$ integrating even $= \frac{\pi^2}{2}$	Q14(c) Required to show that $\ddot{x} = -n^2(x-x_0)$ Given $x = 3 + \sin^2 t$ $\dot{x} = 2 \sin t \cdot \cos t$ (chain rule) $\therefore \ddot{x} = 2 \sin t \frac{d}{dt}(\cos t) +$ $\Rightarrow 2 \cos t \cdot \frac{d}{dt}(\sin t)$ $= -2 \sin^2 t + 2 \cos^2 t$ $= 2(1 - \sin^2 t) - 2 \sin^2 t$ $= 2 - 4 \sin^2 t$ & $\sin^2 t = x - 3$ $\therefore \ddot{x} = 2 - 4(x - 3)$ $= 14 - 4x$ $= -4 \left(x - \frac{14}{4} \right)$ OK $\ddot{x} = -(2)^2 \left(x - \frac{7}{2} \right)$ ALTERNATIVE: $x = 3 + \sin^2 t$ $= 3 + \frac{1}{2}(1 - \cos 2t)$ $= \frac{7}{2} - \frac{1}{2} \cos 2t$ $\Rightarrow \dot{x} = \sin 2t$ $\Rightarrow \ddot{x} = 2 \cos 2t$ & $\cos 2t = 7 - 2x$ from $x = \frac{7}{2} - \frac{1}{2} \cos 2t$ $\therefore \ddot{x} = 2(7 - 2x)$ $= -(2)^2 \left(x - \frac{7}{2} \right)$ ✓ for process	n = angular frequency; x_0 = centre of motion Product rule



Suggested Solution (s)	Comments	Suggested Solution (s)	Comments
Q13 (d) (ii) $\tau = \frac{2\pi}{n}$ & $n=2$ from (i) $\therefore \tau = \pi$ seconds (iii) Noting $0 \leq \sin^2 t \leq 1$, then $3 \leq x \leq 4$ with centre of motion obviously $x=3.5$. Initially, $x=3$ (left extremity of interval & since $\tau=\pi$, particle completes 1 cycle, i.e., travels twice the path length. Hence, total distance travelled is 2 cm. Question 14: (a) Suppose, to the contrary, $\log_3 7 = \frac{p}{q}$; $(p, q) = 1$. $\Rightarrow 3^{p/q} = 7$ or equivalently $3^p = 7^q$ As $\log_3 7 > \log_3 3 = 1$, then $p, q \in \mathbb{N}$. The Fundamental Theory of Arithmetic states that the prime-factor decomposition is UNIQUE for any positive integer greater than 1. If $N = 3^p$, i.e., if $N = \underbrace{3 \times 3 \times \dots \times 3}_{p \text{ times}}$; $N \in \mathbb{N}$ as +ve integers closed under multⁿ.	✓ correct answer ✓ for process ALGEBRAIC METHODS AVAILABLE $p \neq q$ co-prime defⁿ of a logarithm $\log$ is an increasing.	then since $3^p = 7^q$, we have two prime factor decompositions for the positive integer N, which is impossible. Hence, we have a contradiction. ALTERNATIVE: From $3^p = 7^q$ $\Rightarrow 3(3^{p-1}) = 7^q$ $\Rightarrow 3 \mid 7^q$ $\Rightarrow 3 \mid 7$ Consequence of Euclid's lemma However $3 \nmid 7$ & so we have a contradiction. Hence, our supposition is false; namely, $\log_3 7$ is <u>not</u> rational (b) $(i-2\lambda j-k) \cdot ((i-\lambda k) + (\lambda i+j-k))$ $= (i-2\lambda j-k) \cdot ((1+\lambda)i + 2j + (-\lambda-1)k)$ Since the result is 6, we have: $(1+\lambda) - 4\lambda + (\lambda+1) = 6$ $\Rightarrow 2 - 2\lambda = 6$ or $\lambda = -2$ (c) Basis Step: When $n=5$, $(2n!) = 10!$ & $(n!)^2 4^{n-1} = (5!)^2 \times 4^4$ $= (120)^2 \times 256$ $= 3686400$ Clearly $3628800 < 3686400$	✓ for attempting proof by contradiction & eliminating logarithm for ✓ coherent proof. ✓ for solution with one error only ✓ for correct solution ✓ for basis step - calculation MUST be shown



2021 Year 12 Mathematics Extension 2 Task 4 SOLUTIONS

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Suggested Solution (s)	Comments	Suggested Solution (s)	Comments
Q14(c) Cont. INDUCTIVE STEP Assume $(2n)! < (n!)^2 \cdot 4^{n-1}$ for some $n=k$; $k \in \mathbb{N} \setminus \{1, 2, 3, 4\}$. Hence $P(k): (2k)! < (k!)^2 \cdot 4^{k-1}$ When $n=k+1$, $(2(k+1))! = (2k+2)!$ $= (2k+2)(2k+1)(2k) \cdot (2k-1) \cdots 3 \cdot 2 \cdot 1$ $= (2k+2)(2k+1) \cdot [(2k)!]$ $< (2k+2)(2k+1) \cdot (k!)^2 \cdot 4^{k-1}$ $< (2k+2)(2k+2) \cdot (k!)^2 \cdot 4^{k-1}$ $= 4[(k+1)!]^2 \cdot (k!)^2 \cdot 4^{k-1}$ $= ((k+1)!)^2 \cdot 4^k$ Hence, $P(k) \Rightarrow P(k+1)$ As $P(1)$ is true, conclude that $(2n)! < (n!)^2 \cdot 4^{n-1}$ $\forall n \in \mathbb{N} \setminus \{1, 2, 3, 4\}$ by induction (d)(i) Equation of line AB given by $\underline{r} = \underline{a} + \lambda(\underline{b} - \underline{a})$ i.e. $\underline{r} = (1-\lambda)\underline{a} + \lambda\underline{b}$; $\lambda \in \mathbb{R}$ If D lies on AB, then we should be able to find a value for λ such that $\underline{r} = \frac{1}{5}(3\underline{a} + 2\underline{b})$	INDUCTIVE STEP ✓✓✓ for correct solution using inductive hypothesis $2k+1 < 2k+2$ i.e. $1 < 2$ ✓✓ for minor logic errors and/or omissions ✓ states IH & attempts to use it to simplify $P(k+1)$ ✓ for equation of line AB ✓ $\lambda = \frac{2}{5}$ $\vec{OD} = \frac{1}{5}\vec{OC}$	That is: $\frac{3}{5}\underline{a} + \frac{2}{5}\underline{b} = (1-\lambda)\underline{a} + \lambda\underline{b}$ Clearly, $\lambda = \frac{2}{5}$ works. (ii) $\vec{OD} = \underline{a} + \frac{2}{5}(\underline{b} - \underline{a})$ $\underline{b} - \underline{a}$ measures the length of AB. $\lambda = 0$ corresponds to the point A. $\lambda = 1$ corresponds to the point B. $\therefore 0 < \lambda < 1$ corresponds to points in the interval "AB" measured from A to B. As $\frac{2}{5} < \frac{1}{2}$, D is closer to A, noting $\lambda = \frac{1}{2}$ would correspond to the midpoint M of "AB". ALTERNATIVE: $\underline{b} - \underline{a}$ can be construed as the vector from A to B. Consequently, $\underline{a} + \frac{1}{2}(\underline{b} - \underline{a})$ would give the midpoint of AB. As $\frac{2}{5} < \frac{1}{2}$, then the point D, with position vector $\vec{OD} = \underline{a} + \frac{2}{5}(\underline{b} - \underline{a})$ would be closer to A than B.	Corresponding scalar eq'ns $\begin{cases} 1-\lambda = \frac{3}{5} \\ \lambda = \frac{2}{5} \end{cases}$ are consistent ✓ for coherent argument



Suggested Solution (s)	Comments
Q14(e) (i) By de Moivre's theorem: $z^n = (\cos \theta)^n = (\cos \theta + i \sin \theta)^n$ & $\bar{z}^n = (\cos \theta)^{-n} = (\cos \theta - i \sin \theta)^{-n}$ $= (\cos \theta + i \sin \theta)^n$ & $= (\cos \theta + i \sin \theta)^{-n}$ $= \cos n\theta + i \sin n\theta$ & $= \cos(-n)\theta + i \sin(-n)\theta$ $= \cos n\theta - i \sin n\theta$ $\therefore z^n - \bar{z}^n = (\cos n\theta + i \sin n\theta) - (\cos n\theta - i \sin n\theta) = 2i \sin n\theta$ i.e., $z^n - \bar{z}^n = 2i \sin n\theta$, as required. (ii) $(z - \frac{1}{z})^5 = z^5 - 5z^4(\frac{1}{z}) + 10z^3(\frac{1}{z})^2 - 10z^2(\frac{1}{z})^3 + 5z(\frac{1}{z})^4 - (\frac{1}{z})^5$ $= z^5 - 5z^3 + 10z - 10z^{-1} + 5z^{-3} - z^{-5}$ $= (z^5 - z^{-5}) - 5(z^3 - z^{-3}) + 10(z - z^{-1})$ $\therefore (z - \frac{1}{z})^5 = 2i \sin 5\theta - 5 \times 2i \sin 3\theta + 10 \times 2i \sin \theta \dots \text{(I)}$ On the other hand, $(z - \frac{1}{z})^5 = (2i \sin \theta)^5$ or $32i^5 \sin^5 \theta \dots \text{(II)}$ Equating (I) & (II) $32i^5 \sin^5 \theta = 2i \sin 5\theta - 10i \sin 3\theta + 20i \sin \theta$ $\Rightarrow 32 \sin^5 \theta = 2 \sin 5\theta - 10 \sin 3\theta + 20 \sin \theta$ or equivalently, $\sin^5 \theta = \frac{1}{16} \sin 5\theta - \frac{5}{16} \sin 3\theta + \frac{5}{8} \sin \theta$ Hence, $a = \frac{1}{16}$, $b = -\frac{5}{16}$ & $c = \frac{5}{8}$.	sin ODD & cos EVEN ✓ correct solution ✓ expands $(z - \frac{1}{z})^5$ correctly + ✓ rearranges binomial expansion into conjugate pairs and $i^5 = i$ we result in (i) successfully + ✓ for correct values for a, b & c.



Suggested Solution (s)

Comments

Question 15

(a) $|\vec{LN}| = |\vec{LM} + \vec{MN}|$
 $= |\vec{a} + \vec{b}|$ ✓ for correct expression

$$|\vec{LN}|^2 = |\vec{a} + \vec{b}|^2$$

$$= (\vec{a} + \vec{b}) \cdot (\vec{a} + \vec{b})$$

$$= |\vec{a}|^2 + 2\vec{a} \cdot \vec{b} + |\vec{b}|^2 \text{ using properties of dot product}$$

By construction $\vec{LM}$ & $\vec{MN}$ are orthogonal & so $\vec{a} \cdot \vec{b} = 0$

$\therefore |\vec{LN}|^2 = |\vec{a}|^2 + |\vec{b}|^2$, i.e., $|\vec{LN}|^2 = |\vec{LM}|^2 + |\vec{MN}|^2$,
as required

(b) For $\int x^2 \sqrt{1-x^2} dx$, let $x = \sin \theta$, i.e., $\theta = \sin^{-1}(x)$.

Then $dx = \cos \theta d\theta$ & the integral becomes:-

$$\int \sin^2 \theta \cdot \sqrt{1 - \sin^2 \theta} \cdot \cos \theta \cdot d\theta = \int \sin^2 \theta \cdot \cos^2 \theta d\theta$$

$$= \frac{1}{4} \int (2\sin \theta \cdot \cos \theta)^2 d\theta \text{ or } \frac{1}{4} \int \sin^2 2\theta d\theta ; \sin^2 \theta = \frac{1}{2} (1 - \cos 2\theta)$$

$$= \frac{1}{8} \int (1 - \cos 4\theta) d\theta$$

$$= \frac{1}{8} \left(\theta - \frac{\sin 4\theta}{4} \right) + C$$

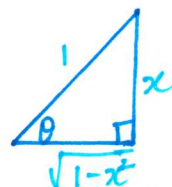
$$= \frac{1}{8} \left(\theta - \frac{2\sin 2\theta \cdot \cos 2\theta}{4} \right) + C$$

$$= \frac{1}{8} \left(\theta - \frac{4\sin \theta \cdot \cos \theta \cdot (1 - 2\sin^2 \theta)}{4} \right) + C$$

$$= \frac{1}{8} \left(\sin^{-1}(x) - x \cdot \sqrt{1-x^2} \cdot (1 - 2x^2) \right) + C$$

or

$$\frac{\sin^{-1}(x) + \sqrt{1-x^2} \cdot (2x^3 - x)}{8} + C, \text{ as required.}$$



$$\begin{cases} \sin \theta = x \\ \cos \theta = \sqrt{1-x^2} \end{cases}$$

$$\vec{LM} = \vec{a}$$

$$\vec{MN} = \vec{b}$$

$$|\vec{a}|^2 = \vec{a} \cdot \vec{a}$$

$$|\vec{b}|^2 = \vec{b} \cdot \vec{b}$$

+

✓✓
for coherent argument

✓✓
for correct sol'n
✓✓
substantial progress
✓
basic progress

Question 15(c) (ii)

VERSION 1: From $1 < x_1 < x_2 < \dots < x_n$ with $x_i \in \mathbb{N}$ with x_i not necessarily equal to $x_{i-1} + 1$, we note:

$$\left. \begin{array}{l} x_1 \geq 2 \\ x_2 \geq 3 \\ \vdots \\ x_n \geq n+1 \end{array} \right\} \therefore \begin{array}{l} \frac{1}{x_1} \leq \frac{1}{2} \\ \frac{1}{x_2} \leq \frac{1}{3} \\ \vdots \\ \frac{1}{x_n} \leq \frac{1}{n+1} \end{array}$$

✓✓✓ for argument
✓✓ for substantial progress
✓ for basic progress

In particular: $\frac{1}{x_1^2} + \frac{1}{x_2^2} + \dots + \frac{1}{x_{n-1}^2} \leq \left(\frac{1}{2}\right)^2 + \left(\frac{1}{3}\right)^2 + \dots + \left(\frac{1}{n}\right)^2$.

So $\sum_{i=1}^{n-1} \left(\frac{1}{x_i}\right)^2 \leq \sum_{i=2}^n \left(\frac{1}{i}\right)^2$; Let $k+1 = i \Rightarrow \sum_{i=2}^n \left(\frac{1}{i}\right)^2 = \sum_{k=1}^{n-1} \frac{1}{(k+1)^2}$

$$\therefore \sum_{i=1}^{n-1} \left(\frac{1}{x_i}\right)^2 \leq \sum_{k=1}^{n-1} \frac{1}{(k+1)^2} < \sum_{k=1}^{n-1} \frac{1}{k(k+1)} \text{ using (i)}$$

$$= \sum_{k=1}^{n-1} \left(\frac{1}{k} - \frac{1}{k+1} \right)$$

$$= 1 - \frac{1}{2} + \frac{1}{2} - \frac{1}{3} + \dots$$

$$\vdots \frac{1}{n-2} - \frac{1}{n-1}$$

$$+ \frac{1}{n-1} - \frac{1}{n}$$

$$= 1 - \frac{1}{n}$$

Consequently,

$$\sum_{i=1}^{n-1} \left(\frac{1}{x_i}\right)^2 < 1 - \frac{1}{n}; n \in \mathbb{N}$$

< 1 , as required.

Question 15(c) (i) VERSION 1

$$\frac{1}{(k+1)^2} < \frac{1}{k(k+1)}$$

✓ for correct argument

$$\Leftrightarrow k(k+1) < (k+1)^2; k \in \mathbb{N}$$

$$\Leftrightarrow k^2 + k < k^2 + 2k + 1$$

$$\Leftrightarrow 0 < k+1, \text{ which is true}$$

VERSION 2 $k+1 > k (> 0)$

$$\Rightarrow \frac{1}{k+1} < \frac{1}{k}$$

$$\Leftrightarrow \frac{1}{(k+1)^2} < \frac{1}{k(k+1)} \text{ as } \frac{1}{k+1} > 0$$

Question 15 (a) (ii)

VERSION 2: We have $\frac{1}{(k+1)^2} < \frac{1}{k(k+1)}$ or equivalently $\frac{1}{k^2} < \frac{1}{(k-1)k}$

$$= \frac{1}{k} - \frac{1}{k+1} \qquad = \frac{1}{k-1} - \frac{1}{k}.$$

So $\frac{1}{x_1^2} < \frac{1}{x_{1-1}} - \frac{1}{x_1}$ Now $x_1 > 1 \Rightarrow x_{1-1} \geq 1$

$$\leq 1 - \frac{1}{x_1} \qquad \Rightarrow \frac{1}{x_{1-1}} \leq 1 \quad *$$

& $\frac{1}{x_2^2} < \frac{1}{x_{2-1}} - \frac{1}{x_2}$ with $x_2 > x_1 \Rightarrow x_{2-1} \geq x_1$

$$\Rightarrow \frac{1}{x_{2-1}} \leq \frac{1}{x_1}$$

$$\leq \frac{1}{x_1} - \frac{1}{x_2}$$

$\vdots$

$\frac{1}{x_i^2} < \frac{1}{x_{i-1}} - \frac{1}{x_i}$ with $x_i > x_{i-1} \Rightarrow x_{i-1} \geq x_{i-1}$

$$\Rightarrow \frac{1}{x_{i-1}} \leq \frac{1}{x_{i-1}}$$

$$\leq \frac{1}{x_{i-1}} - \frac{1}{x_i}$$

$\therefore \frac{1}{x_1^2} + \frac{1}{x_2^2} + \frac{1}{x_3^2} + \dots + \frac{1}{x_{n-1}^2} < \left(1 - \frac{1}{x_1}\right) + \left(\frac{1}{x_1} - \frac{1}{x_2}\right) + \left(\frac{1}{x_2} - \frac{1}{x_3}\right) + \dots + \left(\frac{1}{x_{n-2}} - \frac{1}{x_{n-1}}\right)$

✓✓✓ for argument
✓✓ for substantial progress
✓ for basic progress

$$= 1 - \frac{1}{x_{n-1}}$$

< 1 as $x_{n-1} > 1$; i.e., $x_{n-1} \in \mathbb{N} \setminus \{1\}$

* We have $\frac{1}{x_1^2} < \frac{1}{x_{1-1}} - \frac{1}{x_1} \Rightarrow \frac{1}{x_1^2} < 1 - \frac{1}{x_1}$

$$\leq 1 - \frac{1}{x_1}$$

& in general: $\frac{1}{x_i^2} < \frac{1}{x_{i-1}} - \frac{1}{x_i} \Rightarrow \frac{1}{x_i^2} < \frac{1}{x_{i-1}} - \frac{1}{x_i}$

$$\leq \frac{1}{x_{i-1}} - \frac{1}{x_i}$$



Suggested Solution (s)

Comments

Question 15 (d) (i) Taking the positive sense of all vector quantities in the direction of motion, i.e., vertically downwards, we can apply Newton's 2ND Law as follows:

$$m\ddot{x} = mg - mkv^2$$

$$\Rightarrow \ddot{x} = g - kv^2$$

$$\Rightarrow v \cdot \frac{dv}{dx} = g - kv^2$$

$$\Rightarrow \int \frac{v dv}{g - kv^2} = \int dx$$

$$\Rightarrow -\frac{1}{2k} \int \frac{-2kv}{g - kv^2} = \int dx$$

$$\Rightarrow -\frac{1}{2k} \ln |g - kv^2| = x + C$$

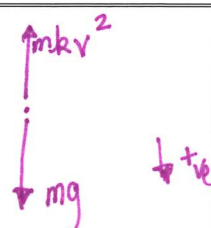
$$\& \quad x=0 \text{ when } v=0 \Rightarrow C = -\frac{1}{2k} \ln(g)$$

$$\text{Consequently, } x = \frac{1}{2k} \ln(g) - \frac{1}{2k} \ln(g - kv^2)$$

$$\text{OR } x = \frac{1}{2k} \ln \left| \frac{g}{g - kv^2} \right|$$

(ii) Firstly, we recognise that terminal velocity is achieved when $\ddot{x} = 0 \Rightarrow g - kv^2 = 0$

$$\Rightarrow v_T = \sqrt{\frac{g}{k}} \quad \& \text{ so } u = \sqrt{\frac{g}{k}}$$



Force diagram

Variables Separable Approach

$$\int \frac{f'(x)}{f(x)} dx = \ln |f(x)| + C$$

$$\ln\left(\frac{a}{b}\right) = \ln(a) - \ln(b)$$

ALTERNATIVE SOLUTIONS AVAILABLE - SEE SUPPLEMENT

... Continued Over



Suggested Solution (s)

Comments

Q15(d) (ii) Cont

The appropriate acceleration equation is $\frac{dv}{dt} = g - kv^2$

$$\Rightarrow \frac{dv}{dt} = k \left(\frac{g}{k} - v^2 \right)$$
$$= k(u^2 - v^2)$$

$$\Rightarrow \int \frac{dv}{u^2 - v^2} = k \int dt$$

$$\Rightarrow \frac{1}{2u} \ln \left| \frac{u+v}{u-v} \right| = kt + C_1$$

$$\int \frac{dx}{a^2 - x^2} = \frac{1}{2a} \ln \left| \frac{a+x}{a-x} \right| + C$$

Standard Partial Fractions Result

When $t=0$, $v=0 \Rightarrow C_1=0$.

$$\text{So } kt = \frac{1}{2u} \ln \left| \frac{u+v}{u-v} \right|$$

By data, $t=T$ when $v = \frac{u}{2}$ & so we have:-

$$kT = \frac{1}{2u} \ln \left| \frac{u+u/2}{u-u/2} \right|$$

$$\Rightarrow kT = \frac{1}{2u} \ln(3) \text{ upon simplifying}$$

$$\Rightarrow T = \frac{1}{2uk} \ln(3) \quad \& \quad u^2 = \frac{g}{k} \text{ or equivalently } \frac{1}{k} = \frac{u^2}{g}$$

& consequently, $T = \frac{1}{2u} \times \frac{u^2}{g} \ln(3)$, that is,

$$T = \frac{u}{2g} \ln(3), \text{ as required.}$$

$$u = \sqrt{\frac{g}{k}}$$

Variables
Separable
Approach

✓✓✓
Correct
solution

✓✓
Substantial
progress

✓ Basic
progress

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SOLUTIONS
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SEE SUPPLEMENT



Suggested Solution (s)

Comments

Question 16

(a)(i) Consider the horizontal direction firstly.

$$\ddot{x} = -0.1 \dot{x} \text{ or equivalently } \frac{dv}{dt} = -0.1v$$

$$\Rightarrow \int \frac{dv}{v} = -0.1 \int dt$$

$$\Rightarrow \ln(v) = -0.1t + C \quad \& \quad \begin{cases} v = u \text{ when } t = 0 \\ \Rightarrow C = \ln(u) \end{cases}$$

$$\therefore \ln\left(\frac{v}{u}\right) = -0.1t$$

$$\Rightarrow \underline{v = ue^{-0.1t}}$$

$$\text{So } \int \frac{dx}{dt} = \int ue^{-0.1t} dt \Rightarrow x = -10ue^{-0.1t} + C_1 \quad \& \quad \begin{cases} x = 0 \text{ when } t = 0 \\ \Rightarrow C_1 = 10u \end{cases}$$

$$\therefore x = 10u - 10ue^{-0.1t} \text{ or}$$

$$\underline{x(t) = 10u(1 - e^{-0.1t})}, \text{ as required.}$$

Now consider the vertical direction.

$$\ddot{y} = -g - 0.1\dot{y} \Rightarrow \frac{dv}{dt} = -g - 0.1v$$

$$\Rightarrow \int \frac{dv}{g + 0.1v} = - \int dt$$

$$\Rightarrow 10 \int \frac{0.1 dv}{g + 0.1v} = - \int dt$$

$$\Rightarrow 10 \ln(g + 0.1v) = -t + C_2 \quad \& \quad \begin{cases} v = 0 \text{ when } t = 0 \\ \Rightarrow C_2 = 10 \ln(g) \end{cases}$$

$$\therefore 10 \ln(g + 0.1v) = -t + 10 \ln(g)$$

... / Continued Over

Variables
Separable
Approach

✓
process

✓ progress

Variables
Separable
Approach



Suggested Solution (s)

Comments

Q16 Cont (a)(i) Cont

$$10 \ln(g + 0.1v) = -t + 10 \ln(g)$$

$$\Rightarrow 10 \ln(g + 0.1v) - 10 \ln(g) = -t$$

$$\Rightarrow 10 \ln\left(\frac{g + 0.1v}{g}\right) = -t$$

$$\Rightarrow \ln\left(\frac{g + 0.1v}{g}\right) = -0.1t$$

$$\Rightarrow \frac{g + 0.1v}{g} = e^{-0.1t}$$

$$\Rightarrow 0.1v = g(e^{-0.1t} - 1)$$

or

$$v = 10g(e^{-0.1t} - 1) \quad \text{or equivalently} \quad \frac{dy}{dt} = 10g(e^{-0.1t} - 1)$$

$$\text{Therefore} \quad \int \frac{dy}{dt} dt = \int 10g(e^{-0.1t} - 1) dt$$

$$\Rightarrow y = 10g(-10e^{-0.1t} - t) + c_3 \quad \& \quad \begin{cases} y=0 \\ \text{when } t=0 \\ \Rightarrow c_3 = 100g \end{cases}$$

$$\text{So } y = 10g(-10e^{-0.1t} - t) + 100g$$

$$\text{i.e. } \underline{y(t) = 100g(1 - e^{-0.1t}) - 10gt}, \text{ as required.}$$

✓✓✓
correct
solution
for $y(t)$;
✓✓ for
substantial
progress;
✓ for
basic
progress

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Suggested Solution (s)	Comments
Q16 Cont (a) (ii) We have $\dot{x}(t) = u e^{-0.1t} \dots (I)$; $\dot{y}(t) = 100(e^{-0.1t} - 1) \dots (III)$ $x(t) = 10u(1 - e^{-0.1t}) \dots (II)$ $y(t) = 1000(1 - e^{-0.1t}) - 100t \dots (IV)$ VERSION 1: Package hits the ground when $x = 4000$ $\Rightarrow 4000 = 10u(1 - e^{-0.1t})$ $\Rightarrow \frac{400}{u} = 1 - e^{-0.1t}$ $\Rightarrow e^{-0.1t} = \frac{u - 400}{u} \dots (V)$ At impact $\tan(45^\circ) = \left \frac{\dot{y}}{\dot{x}} \right$ or equivalently $\tan(-45^\circ) = \frac{\dot{y}}{\dot{x}}$ $\Rightarrow 1 = \frac{100(1 - e^{-0.1t})}{u e^{-0.1t}}$ or $-1 = \frac{100(e^{-0.1t} - 1)}{u e^{-0.1t}} \dots (VI)$ Substituting (V) into (VI): $1 = \frac{100 \left(1 - \frac{u - 400}{u} \right)}{u \left(\frac{u - 400}{u} \right)} \Rightarrow 1 = \frac{100 \times 400 / u}{u(u - 400) / u}$ $\Rightarrow u(u - 400) = 40000$ $\Rightarrow u^2 - 400u - 40000 = 0$ $\Rightarrow u = \frac{400 \pm \sqrt{(400)^2 + 4(40000)}}{2}$ $\quad = \frac{400 \pm \sqrt{2 \times (400)^2}}{2}$ i.e. $u = 200 \pm 200\sqrt{2}$. However, $u > 0$ So $u = 200 + 200\sqrt{2}$ only. Substituting this equation into (V) gives $e^{-0.1t} = \frac{200 + 200\sqrt{2} - 400}{200 + 200\sqrt{2}} = \frac{200(\sqrt{2} - 1)}{200(\sqrt{2} + 1)} \text{ or } \frac{\sqrt{2} - 1}{\sqrt{2} + 1}$ So $e^{0.1t} = \frac{\sqrt{2} + 1}{\sqrt{2} - 1} \text{ or } 3 + 2\sqrt{2}$	$g = 10 \text{ m/s}^2$ ✓✓✓ for correct solution Impact AT 45° to the HORIZONTAL  ✓✓ for minor errors/omissions Quadratic Formula ✓ basic progress Rationalising denominator

$$\Rightarrow t = 10 \ln(3 + 2\sqrt{2}) \approx 17.6 \text{ s } (17.627471\dots)$$



2021 Year 12 Mathematics Extension 2 Task 4 SOLUTIONS

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Suggested Solution (s)

Comments

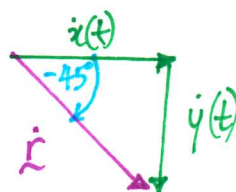
Question 16 (a) (ii) VERSION 2: As before we have:

$$\begin{cases} \dot{x}(t) = 10e^{-0.1t} \\ x(t) = 10u(1 - e^{-0.1t}) \end{cases} ; \begin{cases} \dot{y}(t) = 100(e^{-0.1t} - 1) \\ y(t) = 1000(1 - e^{-0.1t}) - 100t \end{cases}$$

& $4000 = 10u(1 - e^{-0.1t})$ ($x(t) = 4000$)

Also, $\dot{x}(t) = -\dot{y}(t)$ at impact (Angle relative to horizontal is 45°)

$$\therefore 1 = \frac{100(1 - e^{-0.1t})}{10e^{-0.1t}}$$



$$\Rightarrow 10e^{-0.1t} = 100(1 - e^{-0.1t}) \dots (\alpha)$$

From $4000 = 10u(1 - e^{-0.1t}) \Rightarrow u = \frac{400}{1 - e^{-0.1t}} \dots (\beta)$

Substituting (β) into (α) gives $\frac{400}{1 - e^{-0.1t}} \cdot e^{-0.1t} = 100(1 - e^{-0.1t})$

$$\Leftrightarrow \frac{4e^{-0.1t}}{1 - e^{-0.1t}} = 1 - e^{-0.1t}$$

$$\Leftrightarrow \frac{4}{e^{0.1t} - 1} = \frac{e^{0.1t} - 1}{e^{0.1t}}$$

$$\Leftrightarrow 4e^{0.1t} = (e^{0.1t} - 1)^2$$

$$\Leftrightarrow (e^{0.1t})^2 - 6e^{0.1t} + 1 = 0$$

$$\Leftrightarrow e^{0.1t} = \frac{6 \pm \sqrt{32}}{2} \text{ or } 3 \pm 2\sqrt{2}$$

$$\Leftrightarrow t = 10 \ln(3 \pm 2\sqrt{2}) \text{ However } t > 0 \text{ (physical constraint)}$$

& so we reject $t = 10 \ln(3 - 2\sqrt{2})$.

Hence $t = 10 \ln(3 + 2\sqrt{2})$

$\Rightarrow t \approx 17.6 \text{ s as before } (t = 17.627471\dots)$

✓✓✓
for correct solution

✓ for minor errors omissions

✓ for basic progress

Quadratic Formula



Suggested Solution (s)

Comments

Question 16(b) $a^2 + b^2 = c^2$ (Pythagoras' Theorem)

$$\Rightarrow (a^2 + b^2)c = c^3 \text{ or } a^2c + b^2c = c^3$$

$$\begin{aligned} \because a < c \text{ \& } b < c \\ \therefore a^3 < a^2c \text{ \& } b^3 < b^2c \end{aligned} \left. \vphantom{\begin{aligned} \because a < c \text{ \& } b < c \\ \therefore a^3 < a^2c \text{ \& } b^3 < b^2c \end{aligned}} \right\} \text{Consequently } a^3 + b^3 < a^2c + b^2c$$

or equivalently $a^3 + b^3 < c^3$, as required.

ALTERNATIVE SOLUTIONS: VERSION 1 We have $a^2 + b^2 = c^2$ (Pythagoras' Theorem)

Let us assume $a^3 + b^3 < c^3$ or equivalently $a^3 + b^3 < (a^2 + b^2)^{3/2}$

$$\Leftrightarrow (a^3 + b^3)^2 < (a^2 + b^2)^3$$

$$\Leftrightarrow a^6 + 2a^3b^3 + b^6 < a^6 + 3a^4b^2 + 3a^2b^4 + b^6$$

$$\Leftrightarrow 2a^3b^3 < 3a^4b^2 + 3a^2b^4$$

$$\Leftrightarrow 2ab < 3a^2 + 3b^2 \quad ; \quad ab \neq 0$$

$$\Leftrightarrow 0 < 2a^2 + 2b^2 + (a-b)^2 \text{ which is true}$$

as $x^2 > 0 \quad \forall x \in \mathbb{R} \setminus \{0\}$ and certainly for $x > 0$.

VERSION 2:

$$\begin{aligned} \text{We note that } a^4b^2 + a^2b^4 &= (a^2b)^2 + (ab^2)^2 - 2a^2b \cdot ab^2 + 2a^2b \cdot ab^2 \\ &= (a^2b - ab^2)^2 + 2a^3b^3 \end{aligned}$$

$$\text{i.e. } a^4b^2 + a^2b^4 \geq 2a^3b^3 \text{ as } (a^2b - ab^2)^2 \geq 0 \quad \forall a, b \in \mathbb{R} \dots (I)$$

$$\begin{aligned} \text{Also } (a^2 + b^2)^3 &= a^6 + 3a^4b^2 + 3a^2b^4 + b^6 \\ &> a^6 + a^4b^2 + a^2b^4 + b^6 \\ &\geq a^6 + 2a^3b^3 + b^6 \text{ using (I)} \\ &= (a^3 + b^3)^2 \end{aligned}$$

$$\text{So } (a^2 + b^2)^3 > (a^3 + b^3)^2. \text{ However, } a^2 + b^2 = c^2$$

$$\therefore (c^2)^3 > (a^3 + b^3)^2$$

$$\Rightarrow (c^3)^2 > (a^3 + b^3)^2 (> 0)$$

$$\Leftrightarrow c^3 > a^3 + b^3, \text{ as required.}$$

✓✓
for
argument



Suggested Solution (s)

Comments

Question 16 (c) (i),

For $I_{2n+1} = \int_0^1 x^{2n+1} \cdot e^{x^2} dx$, let $\begin{cases} u = x^{2n} \Rightarrow du = 2nx^{2n-1} dx \\ dv = x e^{x^2} dx \Rightarrow v = \frac{1}{2} e^{x^2} \end{cases}$

Then $I_{2n+1} = \left. \frac{1}{2} x^{2n} \cdot e^{x^2} \right|_0^1 - n \int_0^1 x^{2n-1} \cdot e^{x^2} dx$
 $= \frac{e}{2} - n \cdot I_{2n-1}$, as required

(ii) $2 \int_0^1 x^{2n-1} (1+x^2) e^{x^2} dx = 2 \int_0^1 (x^{2n-1} \cdot e^{x^2} + x^{2n+1} \cdot e^{x^2}) dx$

$= 2 (I_{2n-1} + I_{2n+1})$

$= 2 \left(I_{2n-1} + \frac{e}{2} - n I_{2n-1} \right)$ using Reduction Formula from (i)

For $f(x) = x^{2n-1} \cdot e^{x^2}$; f is increasing on $\mathbb{R}$ and, in particular, on $x \in [0, 1]$.

Justification: $f'(x) = e^{x^2} \cdot (2n-1)x^{2n-2} + 2x \cdot e^{x^2} \cdot x^{2n-1}$
 $= e^{x^2} \left((2n-1)x^{2n-2} + 2x^{2n} \right)$
 $= x^{2n-2} \cdot e^{x^2} \cdot (x^2 + 2n-1)$
 $\geq e^{x^2} \cdot (x^2 + 1)$ as $n \in \mathbb{N}$

Also $f(0) = 0$; $f(1) = e > 0 \Rightarrow I_{2n-1} > 0$ (properties of integrals)

Hence $n I_{2n-1} \geq I_{2n-1}$; $n \in \mathbb{N}$.

$\therefore 2 \left(I_{2n-1} + \frac{e}{2} - n I_{2n-1} \right) \leq 2 \left(n I_{2n-1} + \frac{e}{2} - n I_{2n-1} \right)$
 $= 2 \cdot \frac{e}{2} \text{ or } e.$

Hence, $2 \int_0^1 x^{2n-1} (1+x^2) e^{x^2} dx \leq e$, as required.

✓
Correct
Solution
✓ progress
in attempting
to use
integration
by parts

1 mark

+

2 marks
for
coherent
argument

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Question 16 (c) (ii)

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OTHERWISE APPROACH: On $[0, 1]$, $x^{2n-1}(1+x^2)e^{x^2} \geq 0$ with greatest lower bound = 0 & least upper bound = 1. The lub or supremum is achieved when $x=1$.

So $2 \int_0^1 x^{2n-1}(1+x^2) \cdot e^{x^2} dx > 0$, noting glb or infimum achieved when $x=0$.

Also, $2 \int_0^1 x^{2n-1}(1+x^2) \cdot e^{x^2} dx \leq 2 \int_0^1 x^{2n-1}(1+1^2) \cdot e^{1^2} dx$

$$= 4e \int_0^1 x^{2n-1} dx$$

$$= 4e \left[\frac{x^{2n}}{2n} \right]_0^1$$

$$= \frac{2e}{n}$$

$$\leq e \text{ when } \frac{2}{n} \leq 1, \text{ i.e., } n \geq 2 \text{ \& } n \in \mathbb{N}.$$

It only remains to show $2 \int_0^1 x(1+x^2)e^{x^2} dx \leq e$ which is equivalent to showing $\int_0^1 2xe^{x^2} dx + \int_0^1 x^2 \cdot (2xe^{x^2}) dx \leq e$.

Now $\int_0^1 2xe^{x^2} dx = e^{x^2} \Big|_0^1 = e - 1$ & $\int_0^1 \underbrace{x^2}_{u} \cdot \overbrace{(2xe^{x^2})}^{dv} dx = x^2 e^{x^2} \Big|_0^1 - \int_0^1 2xe^{x^2} dx = e - (e - 1)$.

Hence, $2 \int_0^1 x(1+x^2)e^{x^2} dx = (e - 1) + e - (e - 1) = e$

Thus, $2 \int_0^1 x^{2n-1}(1+x^2) \cdot e^{x^2} dx \leq e \quad \forall n \in \mathbb{N}.$

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Question 11 (d) (ii)

Sample Answer:

$$z^7 - 1 = 0$$

$$(z - 1)(z^6 + z^5 + z^4 + z^3 + z^2 + z + 1) = 0$$

$$z^6 + z^5 + z^4 + z^3 + z^2 + z + 1 = 0 \quad (1)$$

$$\frac{z^6 + z^5 + z^4 + z^3 + z^2 + z + 1}{z^3} = \frac{0}{z^3}$$

$$z^3 + z^2 + z + 1 + \frac{1}{z} + \frac{1}{z^2} + \frac{1}{z^3} = 0$$

$$\left(z^3 + \frac{1}{z^3}\right) + \left(z^2 + \frac{1}{z^2}\right) + \left(z + \frac{1}{z}\right) + 1 = 0$$

$$\text{since } z^3 + \frac{1}{z^3} = 2 \cos 3\theta, \quad z^2 + \frac{1}{z^2} = 2 \cos 2\theta \text{ and } z + \frac{1}{z} = 2 \cos \theta$$

$$\Rightarrow 2 \cos 3\theta + 2 \cos 2\theta + 2 \cos \theta + 1 = 0 \quad (2)$$

The solutions of (1) are the non-real seventh roots of unity, so $\theta = \pm \frac{2\pi}{7}, \pm \frac{4\pi}{7}, \pm \frac{6\pi}{7}$

$\therefore$ Since (1) and (2) are equivalent then $\frac{2\pi}{7}, \frac{4\pi}{7}$ and $\frac{6\pi}{7}$ are also solutions to (2).

Let $\theta = \frac{2\pi}{7}$ in (ii):

$$\therefore 2 \cos 3\left(\frac{2\pi}{7}\right) + 2 \cos 2\left(\frac{2\pi}{7}\right) + 2 \cos\left(\frac{2\pi}{7}\right) + 1 = 0$$

$$2\left(\cos\left(\frac{6\pi}{7}\right) + \cos\left(\frac{4\pi}{7}\right) + \cos\left(\frac{2\pi}{7}\right)\right) = -1$$

$$\cos\left(\frac{6\pi}{7}\right) + \cos\left(\frac{4\pi}{7}\right) + \cos\left(\frac{2\pi}{7}\right) = -\frac{1}{2}$$

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15 (d) (ii) (3 marks)

Outcomes Assessed: M1.3/MEX12-6

Targeted Performance Bands: E3-E4

Criteria	Marks
• Provides correct solution	3
• Finds $t = \frac{1}{2\sqrt{kg}} \ln \left \frac{\sqrt{g} + \sqrt{kv}}{\sqrt{g} - \sqrt{kv}} \right $	2
• Correctly separates the variables OR • Finds $\frac{dv}{dv} = \frac{1}{g - kv^2}$	1

Sample Answer:

Relation between v and t :

$$\frac{dv}{dt} = g - kv^2$$

$$\sqrt{k} dt = \frac{\sqrt{k} dv}{g - (\sqrt{k}v)^2}$$

$$\sqrt{k} dt = \frac{\sqrt{k} dv}{g - kv^2}$$

$$\sqrt{k} dt = \left\{ \frac{1}{\sqrt{g} - \sqrt{kv}} + \frac{1}{\sqrt{g} + \sqrt{kv}} \right\} \frac{\sqrt{k} dv}{2\sqrt{g}}$$

$$2\sqrt{kg}t + C = \ln \left| \frac{\sqrt{g} + \sqrt{kv}}{\sqrt{g} - \sqrt{kv}} \right|,$$

$$t = 0, v = 0 \Rightarrow C = 0,$$

$$t = \frac{1}{2\sqrt{kg}} \ln \left| \frac{\sqrt{g} + \sqrt{kv}}{\sqrt{g} - \sqrt{kv}} \right| \quad (1)$$

$$\text{If } v = \frac{U}{2} \text{ and } k = \frac{g}{U^2}, \text{ then from (1) } t = \frac{U}{2g} \ln 3.$$

$$\begin{aligned} \frac{1}{g - kv^2} &= \frac{1}{(\sqrt{g} - \sqrt{kv})(\sqrt{g} + \sqrt{kv})} \\ \frac{1}{(\sqrt{g} - \sqrt{kv})(\sqrt{g} + \sqrt{kv})} &= \frac{A}{(\sqrt{g} - \sqrt{kv})} + \frac{B}{(\sqrt{g} + \sqrt{kv})} \\ v &= A(\sqrt{g} + \sqrt{kv}) + B(\sqrt{g} - \sqrt{kv}) \\ v &= \frac{\sqrt{g}}{\sqrt{k}}, \quad 1 = 2A\sqrt{g} \Rightarrow A = \frac{1}{2\sqrt{g}} \\ v &= -\frac{\sqrt{g}}{\sqrt{k}}, \quad 1 = 2B\sqrt{g} \Rightarrow B = \frac{1}{2\sqrt{g}} \\ \frac{v}{g - kv^2} &= \frac{1}{2\sqrt{g}(\sqrt{g} - \sqrt{kv})} + \frac{1}{2\sqrt{g}(\sqrt{g} + \sqrt{kv})} \end{aligned}$$

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Alternatively:

$$\frac{dv}{dt} = g - kv^2$$

$$\frac{dt}{dv} = \frac{1}{g - kv^2}$$

$$\frac{dx}{dv} = \frac{v}{g - kv^2}$$

$$\begin{aligned} t &= \frac{1}{2\sqrt{g}} \int_0^{\frac{U}{\sqrt{k}}} \left(\frac{1}{\sqrt{g} - \sqrt{kv}} + \frac{1}{\sqrt{g} + \sqrt{kv}} \right) dv \\ &= \frac{1}{2\sqrt{kg}} \left[-\ln|\sqrt{g} - \sqrt{kv}| + \ln|\sqrt{g} + \sqrt{kv}| \right] \\ &= \frac{1}{2\sqrt{kg}} \left[\ln \left| \frac{\sqrt{g} + \sqrt{kv}}{\sqrt{g} - \sqrt{kv}} \right| \right]_{\frac{U}{\sqrt{k}}} \\ &= \frac{1}{2\sqrt{kg}} \left(\ln \left| \frac{\sqrt{g} + \sqrt{k} \times \frac{U}{2}}{\sqrt{g} - \sqrt{k} \times \frac{U}{2}} \right| - \ln \left| \frac{\sqrt{g}}{\sqrt{g}} \right| \right) \\ &= \frac{1}{2\sqrt{kg}} \ln \left| \frac{2\sqrt{g} + U\sqrt{k}}{2\sqrt{g} - U\sqrt{k}} \right| \end{aligned}$$

$$\begin{aligned} \frac{1}{g - kv^2} &= \frac{1}{(\sqrt{g} - \sqrt{kv})(\sqrt{g} + \sqrt{kv})} \\ \frac{1}{(\sqrt{g} - \sqrt{kv})(\sqrt{g} + \sqrt{kv})} &= \frac{A}{(\sqrt{g} - \sqrt{kv})} + \frac{B}{(\sqrt{g} + \sqrt{kv})} \\ v &= A(\sqrt{g} + \sqrt{kv}) + B(\sqrt{g} - \sqrt{kv}) \\ v &= \frac{\sqrt{g}}{\sqrt{k}}, \quad 1 = 2A\sqrt{g} \Rightarrow A = \frac{1}{2\sqrt{g}} \\ v &= -\frac{\sqrt{g}}{\sqrt{k}}, \quad 1 = 2B\sqrt{g} \Rightarrow B = \frac{1}{2\sqrt{g}} \\ \frac{v}{g - kv^2} &= \frac{1}{2\sqrt{g}(\sqrt{g} - \sqrt{kv})} + \frac{1}{2\sqrt{g}(\sqrt{g} + \sqrt{kv})} \end{aligned}$$

At terminal velocity:

$$0 = g - kU^2 \Rightarrow \sqrt{k} = \frac{\sqrt{g}}{U}$$

$$\begin{aligned} \therefore t &= \frac{1}{2\sqrt{g} \left(\frac{\sqrt{g}}{U} \right)} \ln \left| \frac{2\sqrt{g} + U \frac{\sqrt{g}}{U}}{2\sqrt{g} - U \frac{\sqrt{g}}{U}} \right| \\ &= \frac{U}{2g} \ln \frac{3\sqrt{g}}{\sqrt{g}} \\ &= \frac{U}{2g} \ln 3. \end{aligned}$$